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This book has arisen from efforts over many years to find simple and powerful methods for designing industrial control systems. Experience has shown that the classical transfer-function methods were very suitable for isolated loops, but failed in the multivariable situation. The newer state-space methods at first promised success, but came in the end to seem disappointing.

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In control engineering, a state-space representation is a mathematical model of a physical system as a set of input, output and state variables related by first-order differential

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